

Gurobi 9.1 Performance



GUROBI
OPTIMIZATION

The World's Fastest Solver

Zonghao Gu
December 2020

Performance Improvements

- **LP improvements**
 - Dual: 29% faster overall, 66% faster for > 100s models
 - Primal: 17% faster overall, 37% faster for > 100s models
 - Barrier: 15% faster overall, 34% faster for > 100s models
- **MIP improvements**
 - MILP: 5% faster overall, 10% faster for > 100s models
 - MIQP (convex): 6% faster overall, 20% faster for > 100s models
 - MIQCP (convex): 13% faster overall, 57% faster for > 100s models
- **Bilinear or nonconvex MIQCP improvements**
 - 4.1x overall, 9.6x for > 100s models
- **IIS improvements**
 - 2.6x overall, 5.7x for >100s models

LP Performance

LP Improvements

- **Presolve**
 - Improved a presolve reduction
 - Improved dependent row reduction
- **Better decision to solve dual formulation**
 - Use machine learning to decide
 - Including deciding which method to use, primal or dual
- **Weak symmetry improvement**

LP Improvements, Simplex

- **Dual pricing strategy**
 - Improve handling among devex, different types of steepest edge pricing
- **Scaling, especially objective scaling**
- **Perturbation**
- **LU factorization**
 - 2x2 block pivoting
 - Improvement of sparse vs dense treatment
 - Pivoting candidate selection

LP Improvements, Barrier

- **Crossover**
 - Improved ratio test for primal pushes
 - Better numeric handling
 - Initial crossover basis
 - Etc.
- **Barrier parallel improvement**
 - Especially for machines with more than four physical cores

Approaches to Solve Dual Formulation

- **Our approach**
 - Use the original model to formulate the dual model
 - Apply presolve on the dual model
 - Solve the presolved model
- **Alternative approach**
 - Apply presolve to the original model to get the presolved model
 - Formulate the dual model based on the presolved model
 - Solve the dual of the presolved model

Decision to Solve the Dual Formulation

- **Estimate the size of the dual better**
 - Exclude rows and columns in the dual formulation that will obviously be removed by presolve
- **Use machine learning**
 - Find important factors to decide whether to solve the dual formulation
 - We fed the data to scikit-learn – it identified key inputs
 - The aspect ratio, # columns divided by # rows
 - Similar to what we were doing before
 - Decide which method, primal or dual, to solve dual formulation
 - ML gave us a nice formula to decide
 - Mostly expected or understandable, but not all
 - We manually adjusted a bit

Weak Symmetry for LP (aka LP Folding)

- **Example**

- $3w + 3x + 3y + 3z \leq 11$
- $3w + 3x + 2y + 4z \leq 11$
- $3w + 3x + 4y + 2z \leq 11$

- x, y don't look symmetric, but
 - Sum of coefficients = 9 for each column
 - Sum of coefficients = 12 for each row

- **The conditions for weak symmetry**

- Divide the rows and columns into classes
- The sum of the coefficients in a row is equal for each row in the same class
- The sum of the coefficients in a column is equal for each column in the same class
- Objective coefficients and bounds are the same for the variables in the same class
- Rhs and senses are the same for the rows in the same class

Property of LP Weak Symmetry

- **Given a solution x^***
 - Let $x'_j = \frac{1}{n} \sum_{i \in C} x_i^*$, $|C| = n, \forall j \in C$, for any variable class C
 - Easy to show x' is also a feasible solution with the same objective value
 - We can let all the variables in the same class equal
 - All the rows in the same class will be the identical
- **Symmetry reduced model**
 - Combine all the variables in a variable class together
 - by adding up coefficients in the rows
 - Keep only one row for each row class
- **References**
 - Several reports with computational results
 - Many LP solvers have the feature
 - We have it since Gurobi 7.5
 - The key part is to convert nonbasic symmetric solution to basic one

Weak Symmetry Improvement

- **Detection**
 - Catch more general case, including the example in slide 9
 - Speedup: handle sparsity and hashing better
- **Converting to basic solution**
 - Simplex
 - 9.1 uses crossover to convert nonbasic solution to basic one
 - Initial crash basis construction
 - Check many different numeric bad signs, restart if bad enough
 - Heavily tested and refined
 - 9.0 uses the superbasic code to convert
 - Only used for corner cases
 - Barrier
 - 9.1 does crossover twice
 - First crossover on the smaller model is cheap
 - Second crossover with clean solution is numerically more stable
 - 9.0 does crossover once
 - Uncrush the barrier solution (not very clean) to the solution for the large model
 - Crossover with not clean solution on the large model

MIP Performance

- **New heuristics**
 - NoRel heuristic
 - Some new variants of RINS
- **Improvements of existing heuristics**
 - Adjustment on SubMIP heuristic setting
 - Adjustment on Improvement heuristic
- **Performance**
 - Improved MIP performance (optimality) by 1% to 2% overall
 - Greatly improved performance for finding better solutions

Results for Finding Better solutions

- **Test set**
 - All MIPLIB 2017 open problems: 245 models
- **Runs**
 - One hour run with 9.0 default, 9.1 default and 9.1 NoRel heuristic
- **Winning measure:**
 - Solution is at least 1% better in terms of the objective value
 - If one run doesn't find any feasible solution in an hour, then the run finding a feasible solution is considered as winner
- **9.0 default vs 9.1 default**
 - 85 models with the solution difference by more than 1%
 - 16 wins for 9.0 vs 69 wins for 9.1
- **9.1 default vs 9.1 NoRel heuristic**
 - 119 models with the solution difference by more than 1%
 - 29 wins for 9.1 vs 90 wins for 9.1 NoRel

Outer Approximation, Tangent Cut for MIQCP

- **Outer approximation method to solve MIQCP**
 - Solve LP relaxation
 - Add tangent cuts for quadratic constraints to LP relaxation
- **Forms of quadratic constraints**
 - Standard form, SOC (second order cone)
 - $\sum x_i^2 \leq y^2$
 - It often needs to add new variables and to do L'L factorization
 - General form
 - $\sum q_{ij} x_i x_j + \sum a_j x_j \leq b$
 - Input
 - General form, which covers SOC
 - Internal
 - Controlled by parameter PreMIQCPForm
 - -1 auto
 - 0 general form
 - 1 SOC
 - 2 disaggregated SOC

Tangent Cut for Quadratic Constraint

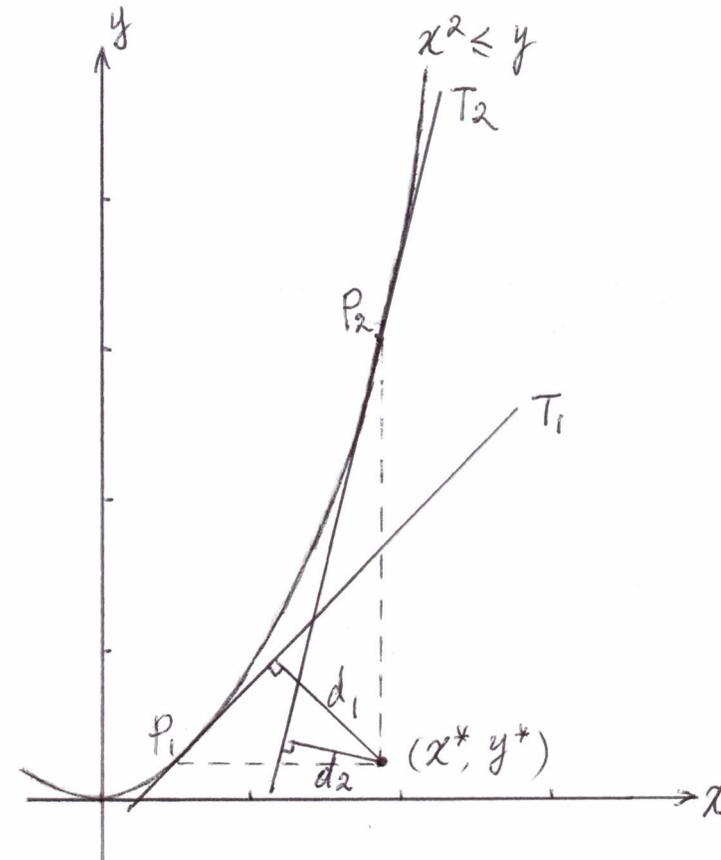
- Many options for cutting off LP relaxation solution x^*
 - Which tangent plane is best?
 - Best = maximum violation?
 - Best = quick separation?

Tangent Cut for SOC

- For given relaxation solution (x^*, y^*) with $\sum x_i^{*2} > y^{*2}$
 - i.e. (x^*, y^*) violates $\sum x_i^2 \leq y^2$
- Let $y' = \sqrt{\sum x_i^{*2}}$ i.e. find a point (x^*, y') on SOC surface
- Use point (x^*, y') to compute the tangent plane
 - It cuts off (x^*, y^*)
 - The distance to (x^*, y^*) is maximum among all the tangent planes cutting off (x^*, y^*)

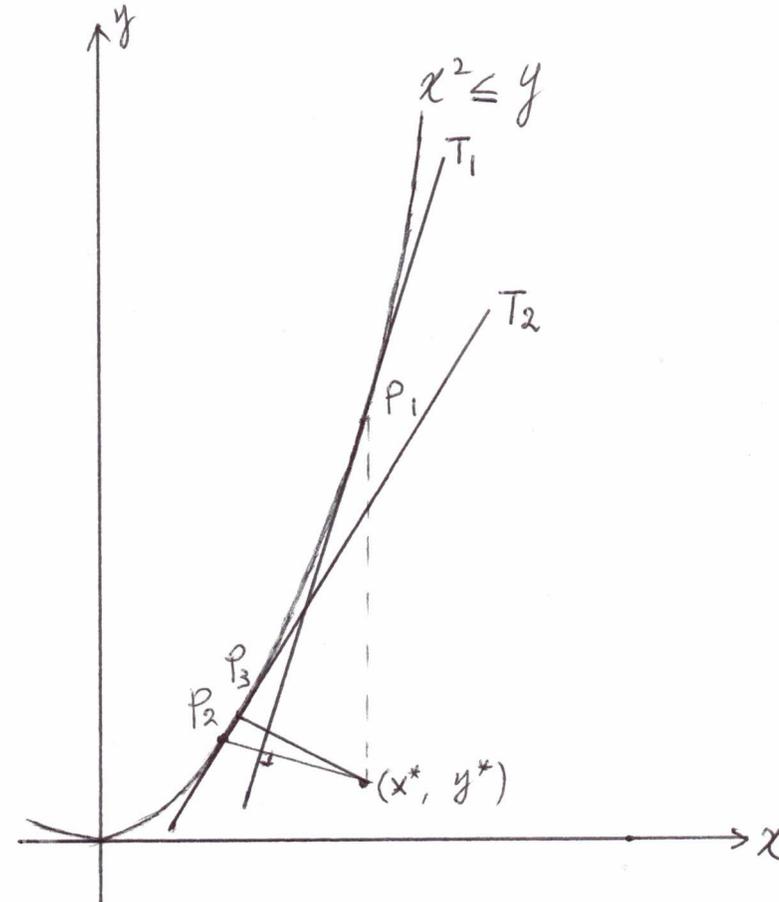
Tangent Cut for Quadratic Constraints in General Form

- How to find a point on surface
 - For given x^* with
$$\sum q_{ij} x_i^* x_j^* + \sum a_j x_j^* > b$$
 - It isn't easy to find a point on surface with the tangent plane cutting off x^*
 - There are many ways to find such a point, example $x^2 \leq y$
 - Violated point $P(x^*, y^*)$
 - Keep y^* unchanged to project to the surface, tangent cut T_1 with distance d_1
 - Keep x^* unchanged to project to the surface, tangent cut T_2 with distance d_2
 - Which tangent plane is better?



Finding Tangent Cut with Maximum Distance

- Our iterative approach
 - Given a violated point (x^*, y^*)
 - Find a reasonably good point P_1 on surface, whose tangent plane cuts off (x^*, y^*) , call tangent plane T_1
 - Project (x^*, y^*) to T_1 and extend it to P_2 , then generate tangent plane T_2
 - Project (x^*, y^*) to T_2 ...
 - Until P_n is very close to the projection of (x^*, y^*) to T_{n-1}
 - Use P_n to generate the tangent cut T_n



Performance Impact of Q Tangent Cut Improvement

- Internal convex MIQCP set
 - 3.3% overall, 10% for > 100s models
- Internal nonconvex MIQCP set
 - 1% overall

Gurobi 9.1 – Performance Summary

- Performance improvements compared to Gurobi 9.0

Algorithm	Overall speed-up	On >100sec models
Primal simplex	17%	37%
Dual simplex	29%	66%
Barrier	15%	34%
MILP	5%	10%
Convex MIQP	6%	20%
Convex MIQCP	13%	57%
Non-convex MIQCP	4.1x	9.6x
IIS detection	2.6x	5.7x